The Poisson Quasi-Maximum Likelihood Estimator: A Solution to the “Adding Up” Problem in Gravity Models

Jean-François Arvis\textsuperscript{a} and Ben Shepherd\textsuperscript{b}

\textsuperscript{a}Senior Economist, the World Bank, 1818 H. St. N.W., Washington, D.C. 20433. Jarvis1@WorldBank.org.

\textsuperscript{b}(Corresponding Author) Principal, Developing Trade Consultants Ltd., 260 W. 52\textsuperscript{nd} St. #22B, New York, NY 10019. Ben@Developing-Trade.com. Phone +1-646-845-9702. Fax +1-646-350-0583.

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Abstract: This paper shows that the Poisson quasi-maximum likelihood estimator applied to the gravity model produces estimates in which, summing across all partners, actual and estimated total trade flows are identical. Other methods such as OLS do not have this desirable property. Indeed, Poisson is the only quasi-maximum likelihood estimator that preserves total trade flows. This result is an additional reason for preferring Poisson as a workhorse gravity model estimator.

Key Words: International Trade; Gravity Model; Poisson; Quasi-Maximum Likelihood Estimator.

JEL Codes: F10; C10.

Word Count: 1,784.
1 Introduction

The gravity model is ubiquitous in the applied international trade literature. Recent contributions have highlighted a number of shortcomings with the traditional approach of log linearization and OLS estimation. In particular, Santos Silva and Tenreyro (2006) provide strong arguments for preferring the Poisson quasi-maximum likelihood estimator. This paper extends their findings by highlighting another desirable property of Poisson: it preserves total trade flows between the actual and estimated bilateral trade matrices in a way that no other quasi-maximum likelihood estimator can. Poisson thus solves the “adding up” problem faced by other gravity model estimators.

The paper proceeds as follows. Section 2 presents a generalized gravity model. Section 3 outlines a simple demonstration of our proposition. Section 4 provides supporting empirical evidence, and Section 5 concludes.

2 The Gravity Model

The CES-based model of Anderson and Van Wincoop (2003) has replaced more traditional formulations to become the benchmark gravity model in the applied international trade literature:

\[
(1) \hat{X}_{ij} = \frac{Y_i E_j}{Y^w} \left( \frac{t_{ij}}{\Pi_i \Pi_j} \right)^{1-s}
\]

\(\hat{X}_{ij}\) models exports from country \(i\) to country \(j\) to be regressed against the actual values \(X_{ij}\). \(E_j\) is expenditure; \(Y_i\) is production; \(Y^w\) is world GDP; \(t_{ij}\) is bilateral trade costs specified in terms of observables, such as geographical distance, i.e. \(\log t_{ij} \sim \log(Distance_{ij})\); and \(s\) is the intra-sectoral elasticity of substitution. Inward multilateral resistance \((P_j)^{(1-s)}\) captures the dependence of economy \(j\)'s imports on trade costs across all suppliers. Outward
multilateral resistance \((\Pi_i)^{(1-s)} = \sum_{j=1}^{N}(P_j)^{(s-1)}w_j(t_{ij})^{(1-s)}\) captures the dependence of economy \(i\)'s exports on trade costs across all destination markets. The \(w\) terms are weights equivalent to each economy’s share in global output or expenditure.

To estimate the model, it is common to use exporter and importer fixed effects to control for GDP and multilateral resistance. Thus, in all generality, the standard gravity model takes the following form:

\[
(2) \quad X_{ij} = k\alpha_i\bar{\alpha}_j t_{ij}^{1-s}e_{ij}
\]

where \(k\) is a constant, \(\alpha_i\) is shorthand for a full set of exporter fixed effects, \(\bar{\alpha}_j\) represents importer fixed effects, and \(e_{ij}\) is a random error term that is statistically independent of the regressors, with \(E(e_{ij}|y_i,\Pi_i,\Pi_j) = 1\). This setup is very close to the more general formulations of gravity found in the regional science literature (e.g., Roy, 2004), in which the fixed effects are interpreted generally as capturing the “repulsive” and “attractive” forces of the exporter and the importer, and a variety of specifications for the trade costs term are considered.

To implement equation (2) empirically, the traditional approach is to use the great circle distance between countries as a proxy for trade costs, and then to obtain OLS estimates of the log-linearized model:

\[
(3) \quad \log(X_{ij}) = \log k + \log \alpha_i + \log \bar{\alpha}_j + \beta \log Distance_{ij} + \log e_{ij}
\]

However, Santos Silva and Tenreyro (2006) highlight two problems with this approach. First, taking the logarithm automatically drops observations for which the reported trade value is zero. This is a significant issue empirically, because zeros are very common. The second problem is that OLS gives inconsistent parameter estimates if the disturbance in (2) \(e_{ij}\) is heteroskedastic, and its variance depends on one or more of the regressors.
Santos Silva and Tenreyro (2006) propose the Poisson quasi-maximum likelihood estimator as a pragmatic solution to both problems. The Poisson regression model is defined in general terms by the discrete distribution:

\[
(4) \Pr(X_{ij} = k | \hat{X}_{ij}) = \frac{e^{-\hat{X}_{ij}}(e^{\hat{X}_{ij}})^k}{k!}, k = 0, 1, 2, \ldots
\]

The expected value and variance are the modeled exports:

\[
(5) E[X_{ij}] = \hat{X}_{ij}; \ Var[X_{ij}] = \hat{X}_{ij}
\]

The log likelihood associated with the distribution is

\[
(6) \log L = \sum_{ij} \log \Pr(X_{ij} | \hat{X}_{ij}) = \sum_{ij} \{-\hat{X}_{ij} + X_{ij} \ast \log \hat{X}_{ij} - \log X_{ij}!\}
\]

Zero observations can be incorporated straightforwardly in the Poisson maximum likelihood (ML) regression. It also naturally accounts for the observed dispersion (according to (5) the coefficient of variation goes as \(\sqrt{\hat{X}_{ij}}\)). Heteroskedasticity can be handled with a robust covariance matrix, and this approach gives consistent estimates regardless of how the data are in fact distributed, i.e. they do not need to be Poisson at all, nor even count data. Recent simulation evidence shows that Poisson performs well compared with other candidate estimators from the literature (Santos Silva and Tenreyro, 2011).

The quasi maximum likelihood (QML) applicable to continuous values derives from (6) and the large number Stirling approximation for \(\hat{X}_{ij}!\), yielding the Theil information like formula:

\[
(7) \log L \approx \sum_{ij} \left\{ \frac{X_{ij} \ast \log \frac{\hat{X}_{ij}}{X_{ij}} + X_{ij} - \hat{X}_{ij}}{X_{ij}} \right\}
\]
3 Poisson and the “Adding Up” Problem

The early gravity literature recognized an additional problem with OLS estimates of the log-linearized model in equation (3) (Tinbergen, 1962; Linnemann, 1966): Jensen’s inequality means that total predicted trade exceeds total actual trade. We refer to this as the “adding up” problem, in the sense that the sum of estimated trade flows for each exporter or importer—i.e., summing across all trading partners in the original bilateral trade matrix—systematically exceeds the total of each country’s actual exports or imports. In Section 4, we show that this effect is quantitatively important. An additional desirable, and unique, property of the Poisson QML is that it solves this “adding up” problem.

We proceed as follows. First, we show that the Poisson QML implies a series of equalities between actual and estimated total trade flows for gravity models with the classical log-linear specification. Then, we prove the following:\(^1\)

THEOREM “The Poisson quasi-maximum likelihood is the only one that equalizes the totals of actual and modeled values for any scale invariant model.”

Scale invariant models are those for which the econometric specification includes, as in (2) and (3), a multiplicative constant \(k\) to be estimated. Models that describe additive quantities, such as trade, production, or population, which are measured in specific arbitrary units (e.g., dollars or tons) necessarily have this property to allow for changes of units, and furthermore “adding up” makes sense for such variables (as opposed to ratios or ordinal variables). Linear dependence in \(k\) means:

\[
\frac{\partial \hat{X}_{ij}}{\partial k} = \frac{1}{k} \hat{X}_{ij}
\]

Maximizing the Poisson QML (7) on the scale \(k\) yields the equalizations of total values:

---

\(^1\) The following development refers to a matrix of flows but it applies to any list of allocation variables and not just a matrix.
The empirical literature primarily uses log linear models for which the predicted values take the form:

\[(9) \hat{X}_{ij} = k e^{D'_{ij} \beta} \]

where \(D'_{ij}\) is the set of independent variables and \(\beta\) the set of regression parameters. Their QML estimate \(\hat{\beta}\) is derived by maximizing (7) given (9), which yields the first order condition (10).

\[(10) 0 = \left(\frac{\partial \log L}{\partial \beta}\right)_{\beta=\hat{\beta}} = \sum_{ij} \left\{ X_{ij} \frac{\partial \log \hat{X}_{ij}}{\partial \beta} - \frac{\partial \hat{X}_{ij}}{\partial \beta} \right\} = \sum_{ij} D'_{ij} (X_{ij} - \hat{X}_{ij}) \]

Hence not only the total flow but the weighted total (or average) of each independent variable is preserved by the Poisson QML for any log-linear model:

\[(11) \sum_{ij} X_{ij} D'_{ij} = \sum_{ij} \hat{X}_{ij} D'_{ij} \]

For dummy variables, equation (11) means that the predicted total flow for the pair \(ij\) where a dummy is true equals the actual one for the same subset. This yields a large set of desirable equalities. For instance, taking exporter and importer dummies as in (2) and (3), total exports and imports by country are preserved. If the model includes regional integration variables, regional trade is conserved as well.

The surprising and important result that actual and predicted total trade flows are exactly equivalent under Poisson has not previously been noted in the literature.

To show that Poisson is the only (quasi-) maximum likelihood estimator that preserves total flows, we consider a general log likelihood function of the form:

\[(12) \log L = \sum_{ij} f(X_{ij}, \hat{X}_{ij}, \sigma) \]
The $\sigma$ are parameters independent of the country pairs, which we can omit without loss of generality. Maximizing the Poisson QML (7) on the scale $k$, yields the generalization of (7) for any pairs of actual and predicted flow values.\(^2\) At the maximum of the likelihood function:

$$
(13) \sum_{ij} \hat{X}_{ij} f_2(X_{ij}, \hat{X}_{ij}) = \sum_{ij} g(X_{ij}, \hat{X}_{ij}) = 0
$$

where $g(X_{ij}, \hat{X}_{ij}) = \hat{X}_{ij} \frac{\partial}{\partial \hat{X}_{ij}} \equiv \hat{X}_{ij} f_2(X_{ij}, \hat{X}_{ij})$. Totally differentiating (13) yields:

$$
(14) \sum_{ij} g_1(X_{ij}, \hat{X}_{ij}) dX_{ij} + \sum_{ij} g_2(X_{ij}, \hat{X}_{ij}) d\hat{X}_{ij} = 0
$$

Since the totals are conserved for the same pair $\{X_{ij}|\hat{X}_{ij}\}$, we also have:

$$
(15) \sum_{ij} dX_{ij} - \sum_{ij} d\hat{X}_{ij} = 0
$$

For these two conditions to impose no further restrictions on the model, they must be proportional (two functional forms with the same kernel are proportional). Hence:

$$
(16) g_1(X_{ij}, \hat{X}_{ij}) = -g_2(X_{ij}, \hat{X}_{ij}) = C \forall i, j
$$

Integration yields:

$$
(17) \hat{X}_{ij} f_2(X_{ij}, \hat{X}_{ij}) = g(X_{ij}, \hat{X}_{ij}) = C(X_{ij} - \hat{X}_{ij}) + D
$$

Since $f$ is QML it should have a local maximum when the two variables are identical, thus $f_2(X_{ij}, X_{ij}) = 0$, and $D = 0$, which means that:

$$
(18) f_2(X_{ij}, \hat{X}_{ij}) = C \left( \frac{X_{ij}}{\hat{X}_{ij}} - 1 \right)
$$

\(^2\) Partial derivative are noted by the subscript 1 or 2 depending on the variable.
Integrating again yields:

\[
(19) \quad \tilde{f}(x_{ij}, \hat{x}_{ij}) = x_{ij} \log \left( \frac{\hat{x}_{ij}}{x_{ij}} \right) - \hat{x}_{ij} + k(x_{ij})
\]

where \( \tilde{f}(x_{ij}, \hat{x}_{ij}) = \frac{f(x_{ij}, x_{ij})}{c} \)

That \( f \) is QML again implies \( f_1(x_{ij}, x_{ij}) = 0 \). Therefore:

\[
(20) \quad f_1(x_{ij}, x_{ij}) = -1 + k'(x_{ij}) = 0
\]

which means that \( k(x_{ij}) = x_{ij} \). Equation 19 therefore becomes the Poisson QML:

\[
(21) \quad \tilde{f}(x_{ij}, \hat{x}_{ij}) = x_{ij} \log \left( \frac{\hat{x}_{ij}}{x_{ij}} \right) - \hat{x}_{ij} + x_{ij} \quad \text{QED}
\]

4 Empirical Implementation

In this section, we use a simple empirical example to show that the “adding up” problem we have identified is quantitatively important, and that Poisson indeed provides an effective solution. To do this, we set up a gravity model using aggregate trade data for 134 importers and 227 exporters for 2009, sourced from UN-Comtrade. We include common trade cost proxies, such as geodesic distance, and dummies for common language, geographical contiguity, colonial links, and a common colonizer. All geographical and historical data are sourced from the CEPII distance dataset. We also include full sets of exporter and importer fixed effects.

Table 1 presents results using OLS (column 1), Poisson (column 2), and Gamma (column 3), as in Santos Silva and Tenreyro (2006). We initially consider only non-zero trade flows. In line with previous work, all estimators provide parameter estimates that are economically meaningful and generally highly statistically significant. However, the bottom line of the table shows that the divergence between actual
and estimated total trade flows is substantial in all cases except for Poisson, where—in line with our theorem—the two are identical.

The same finding is apparent when we include zero trade flows in the estimation sample (columns 4-6). (For OLS, we include zero trade flows by using \( \log(1 + X_{ij}) \) as the dependent variable.) Although parameter estimates are sensible in all four cases, the divergence between actual and estimated total trade flows is very large for OLS, and particularly for Gamma. Again, the Poisson estimates do not suffer from this problem, and reproduce total trade flows exactly.

5 Conclusion

This paper has demonstrated a new and desirable property of the Poisson quasi-maximum likelihood estimator applied to the standard gravity model. In addition to dealing with heteroskedasticity and zero trade flows, the Poisson estimator also solves what we have termed the “adding up” problem. It is the only quasi-maximum likelihood estimator that preserves total flows between the actual and estimated bilateral trade matrices. Our theoretical and empirical findings strengthen the case for using Poisson as the workhorse gravity model estimator.

References


Tables

Table 1: Regression results.

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<th>Excluding Zero Trade Flows</th>
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<th>Including Zero Trade Flows</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>(1) OLS</td>
<td>(2) Poisson</td>
<td>(3) Gamma</td>
</tr>
<tr>
<td>Log(Distance)</td>
<td>-1.569*** (0.000)</td>
<td>-0.712*** (0.000)</td>
<td>-1.416*** (0.000)</td>
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<td>0.340*** (0.000)</td>
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<td>0.281*** (0.002)</td>
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<td>0.170</td>
<td>1.181*** (0.000)</td>
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<tr>
<td>Common Colonizer</td>
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<td>0.345* (0.064)</td>
<td>0.601*** (0.000)</td>
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<td></td>
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<tr>
<td></td>
<td>$100 \cdot \frac{\sum_{i,j} \hat{Y}<em>{ij}}{\sum</em>{i,j} X_{ij}}$</td>
<td></td>
<td>$840.331%$ 100% 502.955%</td>
</tr>
</tbody>
</table>

Note: Prob. values based on robust standard errors adjusted for clustering by country-pair appear in parentheses. Statistical significance is indicated by * (10%), ** (5%), and *** (1%). Estimation method is indicated at the top of each column. The dependent variable is exports, except for column 1 where it is log(exports), and column 5 where it is log(1+exports).